Scaling of Evolutionary Search of Algorithm Space to Speed-Up Scientific Image Understanding Workflows

Nicholas Grabill - University of Michigan Kai Pinckard - Reed College Dirk Colbry - Michigan State University



Outline

- What is Scientific Image Understanding
- Motivating the problem
- Our Solution and how it Scales

Visual Observations

- Long history in Biology
- Traditionally done by hand





Photography

- Changes science
 - Scientists are able to record video without knowing what they will see
 - Cameras may see something the scientists missed
 - Different scientists can view the same data with different scientific questions in mind



Cameras Everywhere

- Transforming how scientists gather data
- Very affordable
- Data is becoming very cheap to gather, so there is a lot more of it



Charge-Coupled Device (CCD)

How are digital images analyzed?



Graduate students are cheap...

Undergraduates are even cheaper!

Also, easy to run in parallel



With enough data we can use machine learning

Serving the Long Tail of Scientific Imaging



Why is automating the long tail of science hard?

- Data annotation can be expensive.
- Features change with every problem
- Projects can't afford an engineer for every new idea
- Not everyone can be an expert in image analysis, so training every scientist doesn't always work
- By the time you are done annotating a training set you may be done with the research!



While

Researcher Annotates Images (in the foreground)

Computers search for solutions (in the background)



Example: Image Segmentation



Original Image



Annotated Ground Truth Label



Example from KOMATSUNA plant dataset: http://limu.ait.kyushu-u.ac.jp/~agri/komatsuna/

Python Skimage.Segmentation Library

- 1. thresholding(image[, ...]) Basic image thresholding (not part of skimage)
- 2. random_walker(data, labels) Random walker algorithm for segmentation from markers.
- 3. active_contour(image, snake)- Active contour model.
- 4. felzenszwalb(image[, ...]) Computes Felsenzwalb2 efficient graph based image segmentation.
- 5. slic(image[, ...]) Segments image asing k-means clustering in Color-(x,y,z) space.
- 6. quickshift(image[, ...]) verments image using quickshift clustering in Color-(x,y) space.
- 7. watershed (image). He find watershed basins in image flooded from given markers.
- 8. chan_vese_mage[, mu, ...])- Chan-Vese segmentation algorithm.
- 9. morphological_geodesic_active_contour(...) Morphological Geodesic Active Contours (MorphGAC).
- 10. morphological_chan_vese(...) Morphological Active Contours without Edges (MorphACWE)
- 11. inverse_gaussian_gradient(image) Inverse of gradient magnitude.
- 12. circle_level_set(...[, ...]) Create a circle level set with binary values.
- 13. checkerboard_level_set(...) Create a checkerboard level set with binary values.



Why Use GAs?

- Can search highly *heterogeneous* search space
- Can search *non-differentiable* search spaces
- Easy to seed search space with known engineered solutions
- Can *scale* easily (task level scaling)
- Output is *human readable*

Part 1: Define Your Population Space

[Algorithm (1-13), option 1, option2, option3, ..., optionN]

 $[5, 244, 0.44, 72, \dots, -28] \dots [2, 10, 0.1, 1, \dots, 1035]$

Part 2: Fitness Function

Original Image



Annotated Ground Truth





Experiments

- Preliminary Scaling results on our local HPC
- Running on multiple Kubernetes Clusters

Scaling Results



Running SEE-Segment the Cloud



Why Use Kubernetes with Docker Containers?

- The Docker Containers *simplify* the setup process by automatically creating the same environment for each SEE-Segment worker
- Using Kubernetes and Docker means that SEE-Segment workers and the SEE-server can be run on any *cloud platform* that supports Kubernetes without any code changes.
- Furthermore, Kubernetes makes *scaling* up the number of SEE-Segment workers as simple changing a single number.



← → C ① Not secure 0.0.0.8080/index

III Apps

See Segment



Upload Files Results

ß

Select an RGB image to learn segmentations on.

Choose File No file chosen

Select a ground truth segmentation label image to use.

Choose File No file chosen

Upload Images



🖈 🚥 🔿 🚳 🧱 📧 🗄

III Apps

See Segment



RGB Image



Current Best



Ground Truth



Segmentation Code:

```
channel_num = 3
if len(img.shape) > 2:
    num_channels = img.shape[2]
    if channel_num < num_channels:
    channel = img[:, :, int(channel_num)]
      else:
    hsv = skimage.color.rgb2hsv(img)
#print(f"working with hsv channel {channel_num-3}")
channel = hsv[:, :, int(channel_num)-3]
else:
      channel = img
pscale = np.max(channel)
my_mx = 0.23 * pscale
my_mn = 0.44 * pscale
output = None</pre>
```

Fitness: 0.06

Parameters:

['CT', 4594, 0.981, 7873, 0.23, 7245, 2159, 10, 0.77, 8233, 6488, 3, 8, 0.0001, 0.44, [1, 1], 3.4, 'small disk', 'checkerboard', 3, 1438, -21, 0.0, 0.0, 0.0]



Nicholas Grabill - University of Michigan

• grabilln@umich.edu

Kai Pinckard - Reed College

• kaidpinck@reed.edu

Dirk Colbry - Michigan State University

• colbrydi@msu.edu

SEE-Insight Team and Alumni:

- Davin Lin (Grinnell College)
- Emma Burleson (Emory University)
- Katrina Gensterblum (Michigan State University)
- Noah Stolz (Rensselaer Polytechnic Institute)
- Nate Britton (Michigan State University)
- Emani Hunter (Michigan State University)
- Cameron Hurley (Michigan State University)
- Paul Ezimako (Texas Southern University)
- Raymond Lesiyon (Michigan State University)
- Alexander Eboru (Wayne State University)
- Amon Harris (North Carolina Central University)